

Patent Abstracts of Japan

PUBLICATION NUMBER : 2002127058
PUBLICATION DATE : 08-05-02

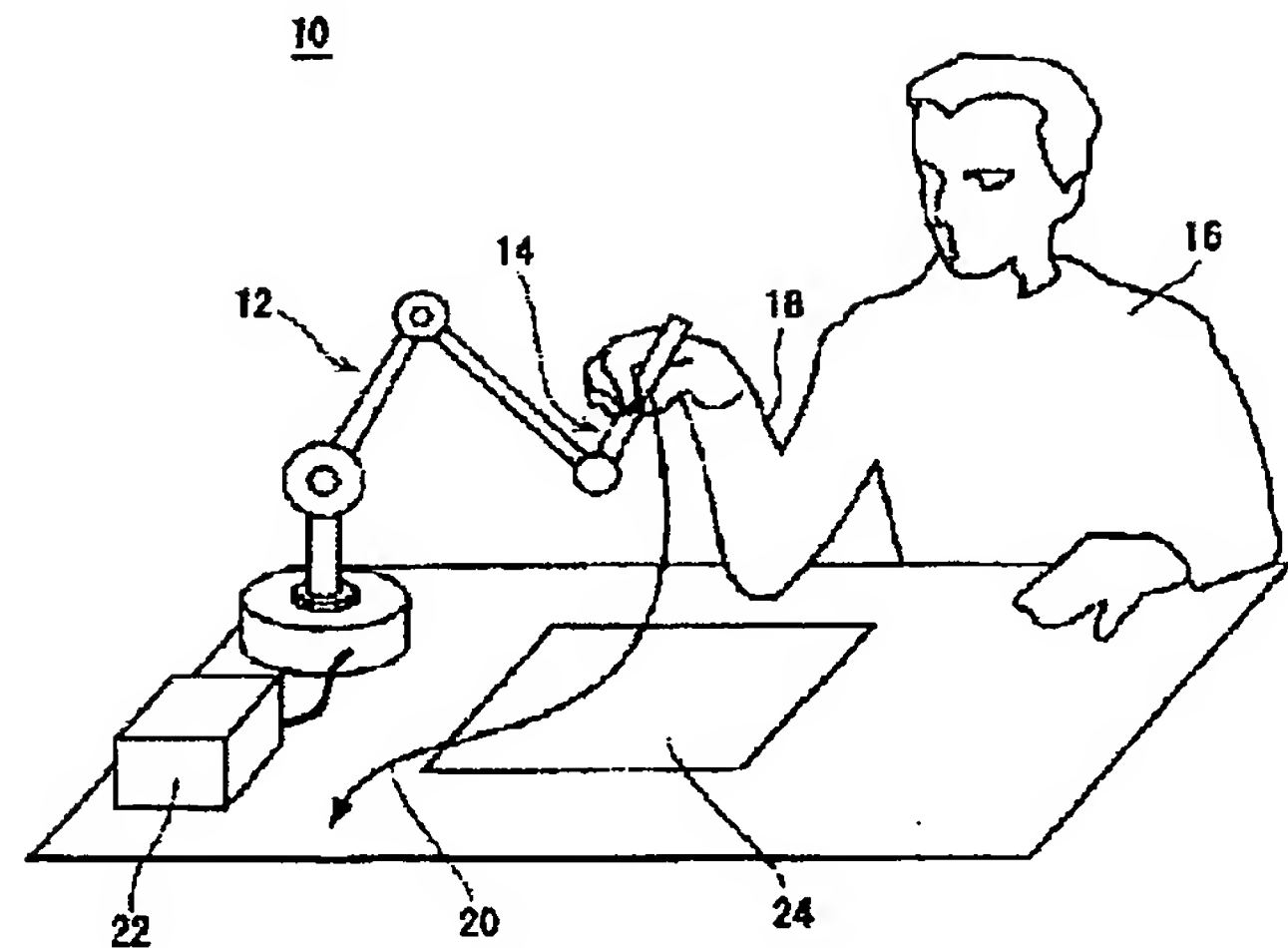
APPLICATION DATE : 26-10-00
APPLICATION NUMBER : 2000326304

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INT.CL. : B25J 9/22 B25J 13/00 // A61H 1/02

TITLE : TRAINING ROBOT, TRAINING ROBOT
SYSTEM AND TRAINING ROBOT
CONTROL METHOD



ABSTRACT : PROBLEM TO BE SOLVED: To secure safety by imparting flexibility of restriction to a motional trajectory and time, and perform a smooth action for reducing an unpleasant feeling and a burden.

SOLUTION: This training robot 10 takes three-dimensional action of the body by a person on the basis of training and skill in a robot controller 22 including a computer for controlling a robot arm 12 as teaching data, and presents the motion again to a patient or a user 16 or a trainee directly or via a network 52 to perform a training action on the limbs, for example, the upper limbs of the person supported by the robot arm.

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